

Vector Kinematics in Two Dimensions:

$$v = v_0 + at \qquad \bar{v} = \frac{v + v_0}{2}$$

$$v^2 = v_0^2 + 2ad \qquad d = v_0t + \frac{1}{2}at^2$$

Vector Dynamics:

$$F_{\text{net}} = ma \qquad F_g = mg$$

$$F_{\text{fr}} = \mu F_N$$

Work, Energy, and Power:

$$W = Fd \qquad E_p = mgh$$

$$E_k = \frac{1}{2}mv^2 \qquad P = \frac{W}{t}$$

Momentum:

$$p = mv \qquad \Delta p = F\Delta t$$

Equilibrium:

$$\tau = Fd$$

Circular Motion:

$$a_c = \frac{v^2}{r} = \frac{4\pi^2 r}{T^2}$$

Gravitation:

$$F = G \frac{m_1 m_2}{r^2} \qquad E_p = -G \frac{m_1 m_2}{r}$$

**You may detach this page for convenient reference.
Exercise care when tearing along perforations.**

Electrostatics:

$$F = k \frac{Q_1 Q_2}{r^2} \quad E = \frac{F}{Q}$$

$$\Delta V = \frac{\Delta E_p}{Q} \quad E = \frac{\Delta V}{d}$$

$$E_p = k \frac{Q_1 Q_2}{r} \quad V = \frac{kQ}{r}$$

Electric Circuits:

$$I = \frac{Q}{t} \quad V = IR$$

$$V_{\text{terminal}} = \mathcal{E} \pm Ir \quad P = IV$$

Electromagnetism:

$$F = BIl \quad F = QvB$$

$$B = \mu_0 n I = \mu_0 \frac{N}{l} I \quad \mathcal{E} = Blv$$

$$\Phi = BA \quad \mathcal{E} = -N \frac{\Delta \Phi}{\Delta t}$$

$$V_{\text{back}} = \mathcal{E} - Ir$$

$$\frac{V_s}{V_p} = \frac{N_s}{N_p} = \frac{I_p}{I_s}$$